# Lecture 2: <br> Data structures for disjoint sets 

October 7, 2020

## Preliminaries

MAIN IDEA: Group $n$ distinct elements into a collection of disjoint sets; the following operations should be efficient:

- Finding the set to which a given element belongs.
- Uniting two sets.

Content of this lecture
(1) The disjoint-set data structure + specific operations
(2) A simple application
(3) Concrete implementations based on

- linked lists
- rooted trees

4 Discussion: the Ackermann function

## Disjoint-set data structure

## Main features

Container for a collection $\mathcal{S}=\left\{S_{1}, S_{2}, \ldots, S_{n}\right\}$ of disjoint dynamic sets. ( $A, B$ are disjoint sets if $A \cap B=\emptyset$.)

- Each set is identified by some member of the set, called its representative
$\triangleright$ REQUIREMENT: If we ask for the representative of a dynamic set twice without modifying the set, we should get the same answer.


## Desirable operations

$\triangleright \operatorname{MAKESET}(x)$ : creates a new set consisting of $x$ only. (Requirement: $x$ is not already in another set.)
$\triangleright \operatorname{UNION}(x, y)$ : unites the sets that contain $x$ and $y$, say $S_{x}$ and $S_{y}$, into a new set that is their union. The sets $S_{x}$ and $S_{y}$ can be destroyed.
$\triangleright \operatorname{FINDSET}(x)$ : returns a pointer to the representative of the unique set containing element $x$.

## Disjoint-set data structure

Application: Determining the connected components of an undirected graph

Assumption: $G=(V, E)$ is an undirected graph.
(1) Computing the connected components of $G$ :

ConnectedComponents( $G$ )
1 for each node $v \in V$
2 MakeSet(v)
3 for each edge $(u, v) \in E$
4 if $\operatorname{FindSet}(u) \neq \operatorname{FindSet}(v)$
$5 \operatorname{UNION}(u, v)$
(2) Determine if two elements are in the same component:

SAmeComponent $(u, v)$
1 if $\operatorname{FindSet}(u)=\operatorname{FindSet}(v)$
2 return True
3 return FALSE

## Disjoint-set data structure

Application: Determining the connected components of an undirected graph

Example (A graph with 4 connected components)


Edge


## Disjoint sets

## A linked-list representation

## Main ideas

- Each set is represented by a linked list.
- The first element in each linked list is the representative of the set.
- Each object in the linked list contains
- A pointer to the next set element
- A pointer back to the set representative
- MakeSet $(x)$ and $\operatorname{FindSet}(x)$ are straightforward to implement
- They require $O(1)$ time.

Q1: How to implement $\operatorname{UNION}(x, y)$ ?
Q2: What is the time complexity of $\operatorname{UNION}(x, y)$ ?

## Disjoint sets

## A linked-list representation

## Example

(1) Linked-list representations of sets $\{b, c, h, e\}$ and $\{d, f, g\}$

(2) Linked-list representation of their union


## Disjoint sets

## A linked-list representation

Implementation of $\operatorname{UNION}(x, y)$

- Append $x$-s list onto the end of $y$-s list and update all elements from $x$-s list to point to the representative of the set containing $y$
$\Rightarrow$ time linear in the length of $x$-s list.


## Disjoint sets

## A linked-list representation

Implementation of $\operatorname{UNION}(x, y)$

- Append $x$-s list onto the end of $y$-s list and update all elements from $x$-s list to point to the representative of the set containing $y$
$\Rightarrow$ time linear in the length of $x$-s list.
Some sequences of $m$ operations may require $\Theta\left(m^{2}\right)$ time (see next slide)


## Disjoint sets represented by linked lists

## Example

A sequence of $m$ operations that takes $\Theta\left(m^{2}\right)$ time

| Operation | Number of objects updated |
| :---: | :---: |
| $\operatorname{MAKESET}\left(x_{1}\right)$ | 1 |
| $\operatorname{MAKESET}\left(x_{2}\right)$ | 1 |
| $\vdots$ | $\vdots$ |
| $\operatorname{MAKESET}\left(x_{q}\right)$ | 1 |
| $\operatorname{UnION}\left(x_{1}, x_{2}\right)$ | 1 |
| $\operatorname{UnION}\left(x_{2}, x_{3}\right)$ | 2 |
| $\operatorname{UnIoN}\left(x_{3}, x_{4}\right)$ | 3 |
| $\vdots$ | $\vdots$ |
| $\operatorname{UnIoN}\left(x_{q-1}, x_{q}\right)$ | $q-1$ |

The number of MAKESET ops. is $n=\lceil m / 2\rceil+1$, and $q=m-n$.
Total time spent: $\Theta\left(n+q^{2}\right)=\Theta\left(m^{2}\right)$ because $n=\Theta(m)$ and $q=\Theta(m) \Rightarrow$ amortized time of an operation is $\Theta(m)$.

## Towards a faster implementation

## Disjoint-set forests

MAIN IDEA: Represent sets by rooted trees, with each node containing one member and each tree representing one set.

- A disjoint-set forest is a set of rooted trees, where each member points only to its parent.


## Example



## Towards a faster implementation

## Disjoint-set forests

Implementation of disjoint set operations:

- MakeSet $(x)$ : creates a tree with just one node.
- FindSet $(x)$ : follows the parent pointers from a node until it reaches the root of the tree.
- The nodes visited on the path towards the root constitute the find path.
- UNION $(x, y)$ : causes the root of one tree to point to the root of the other tree.


## Remarks

(1) A sequence of $n$ UNION operations may create a tree which is just a linear chain of nodes
$\Rightarrow$ Disjoint-set forests have not improved the linked list representation.
(2) We need 2 more heuristically improvements: union by rank and path compression.

## Disjoint-set forests

## Heuristic 1: union by rank

Implementation of $\operatorname{UNION}(x, y)$

- MAIN IDEA: make the root of the tree with fewer nodes point to the root of the tree with more nodes.
- Each node has a rank that approximates the logarithm of the size of the subtree rooted at each node and also an upper bound of the height of the node.
$\Rightarrow$ perform union by rank: the root with smaller rank is made to point to the root with larger rank during the operation $\operatorname{UNION}(x, y)$.


## Disjoint-set forests

## Heuristic 2: path compression

Main idea: During FindSet operations, each node on the find path will be made to point directly to the root.

## Example

Path compression during the operation $\operatorname{FindSET}(a)$.

(a) before executing FindSET(a)

(b) after executing FindSET(a)

## Disjoint-set forests

## Pseudocode for main operations (1)

- With each node $x$, we maintain the int value $x$.rank which is an upper bound on the height of $x$ (the number of edges on the longest path between $x$ and a descendant leaf) The initial rank of a node in a newly created singleton tree is 0 .
MakeSet ( $x$ )

1. $x \cdot p=x$
2. $x \cdot$ rank $=0$

Union $(x, y)$

1. $\operatorname{Link}(\operatorname{FindSet}(x), \operatorname{FindSet}(y))$
$\operatorname{LINK}(x, y)$
1 if $x$.rank > y.rank
$2 \quad y \cdot p=x$
3 else $x . p=y$
4 if $x . r a n k==y . r a n k$
$5 \quad$ y.rank $=y \cdot r a n k+1$

## Disjoint-set forests

## Pseudocode for FindSET( $x$ )

FINDSET is a two-pass method:
(1) It makes one pass up the find path to find the root
(2) it makes a second pass back down the path to update each node so that it points directly to the root.
FindSet $(x)$
1 if $x \neq x$. $p$
$2 x . p=\operatorname{FindSET}(x . p)$
3 return X.p
$\triangleright$ Each call of $\operatorname{FINDSET}(x)$ returns $x . p$ in line 3.
$\triangleright$ If $x$ is the root then line 2 is not executed and $p[x]=x$ is returned.

- This is the case when recursion bottoms out.
$\triangleright$ Otherwise, line 2 is executed and the recursive call with parameter x.p returns (a pointer to) the root.
$\triangleright$ Line 2 updates $x$ to point directly to the root.


## Disjoint-set forests

## Effect of heuristics on running time

Assumptions:
$n=$ number of MAKESET operations, $m=$ total number of MAKESET, UNION and FINDSET operations.

- Union by rank has time complexity $O(m \log n)$ [Cormen et al., 2000]
- When we use both path compression and union by rank, the operations have worst-case time complexity $O(m \cdot \alpha(m, n))$ where $\alpha(m, n)$ is the very slowly growing inverse of Ackermann's function (see next slides.)
- On all practical applications of a disjoint-set data structure, $\alpha(m, n) \leq 4$.
- $\Rightarrow$ we can view the running time as linear in $m$ in all practical situations.


## Ackermann's function and its inverse

## Preliminary notions

$\triangleright$ Let $g: \mathbb{N} \rightarrow \mathbb{N}$ be the function defined recursively by

$$
g(i)= \begin{cases}2^{1} & \text { if } i=0 \\ 2^{2} & \text { if } i=1, \\ 2^{g(i-1)} & \text { if } i>1\end{cases}
$$

Intuition: $i$ gives the height of the stack of 2 s that make up the exponent.
$\triangleright$ For all $i \in \mathbb{N}$ we define

$$
\lg ^{(i)}(n)= \begin{cases}n & \text { if } i=0 \\ \lg \left(\lg ^{(i-1)}(n)\right) & \text { if } i>0 \text { and } \lg ^{(i-1)}(n)>0, \\ \text { undefined } & \text { if } i>0 \text { and } \lg ^{(i-1)}(n) \leq 0 \text { or } \lg ^{(i-1)}(n) \text { is undefined. }\end{cases}
$$

where Ig stands for $\log _{2}$
$\triangleright \lg ^{*}(n)=\min \left\{i \geq 0 \mid \lg ^{(i)}(n) \leq 1\right\}$.
REMARK: $\lg ^{*}\left(2^{g(n)}\right)=n+1$.

## References

- Chapter 22: "Data Structures for Disjoint Sets" of
- T. H. Cormen, C. E. Leiserson, R. L. Rivest. Introduction to Algorithms. MIT Press, 2000.

