Algorithms and Data Structures (II)

Gabriel Istrate

March 4, 2020

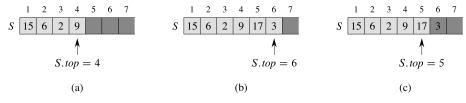
Gabriel Istrate Algorithms and Data Structures (II)

First of all ...



- A Stack is a sequential organization of items in which the last element inserted is the first element removed. They are often referred to as LIFO, which stands for "last in first out."
- Examples: letter basket, stack of trays, stack of plates.
- Only element that may be accessed: the one that was most recently inserted.
- There are only two basic operations on stacks, the push (insert), and the pop (read and delete).

Stacks: Implementation



- (a). Stack representing set $S = \{2, 6, 9, 15\}$.
- (b). After PUSH(S,3).
- (c). After POP(S).

• We can use the stack class we just defined to parse and evaluate mathematical expressions like:

$$5 * (((9+8) * (4 * 6)) + 7)$$

• First, we transform it to postfix notation:

598 + 46 * * 7 + *

- Usual form for arithmetic expressions: infix. term1 op term2.
- Postfix notation: term1 term2 op.
- How to convert infix to postfix: later !

Then, the following C++ routine uses a stack to perform this evaluation:

1 char c: Stack $\operatorname{acc}(50)$; 2 $3 \quad \text{int } \mathbf{x};$ 4 while (cin.get(c)) $5 \{$ 6 x = 0: 7 while (c == ', ') cin.get(c); 8 if (c == '+') x = acc.pop() + acc.pop();if (c == '*') x = acc.pop() * acc.pop();9 10 while (c > 0' && c < 9')11 $x = 10^*x + (c-'0'); cin.get(c);$ 12 $\operatorname{acc.push}(\mathbf{x});$ 13} 14 cout $<< \operatorname{acc.pop}()$;

- We read one character at a time in c.
- In x we compute the value of the currently evaluated expression.
- After computing it we push the value on the stack we will need it later.
- When reading an op we take the last two value off the stack and apply the op on them and assign this to x.
- When reading a digit we update value of x by making the last read digit the least significant one.

- Algorithms (later).
- Recursion removal.
- Reversing things.
- Procedure call and procedure return is similar to matching symbols:
 - When a procedure returns, it returns to the most recently active procedure.
 - When a procedure call is made, save current state on the stack. On return, restore the state by popping the stack.
 - Formal languages: pushdown automata.



• The ubiquitous "first-in first-out" container (FIFO)

Queues

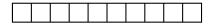
- The ubiquitous "first-in first-out" container (FIFO)
- Interface

 - Dequeue(Q) extracts the element at the head of queue Q

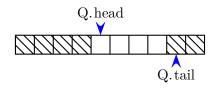
Queues

- The ubiquitous "first-in first-out" container (FIFO)
- Interface
 - $\bullet \ Enqueue(Q,x) \ adds \ element \ x \ at \ the \ back \ of \ queue \ Q$
 - Dequeue(Q) extracts the element at the head of queue Q
- Implementation
 - Q is an array of fixed length Q.length
 - i.e., **Q** holds at most **Q**.length elements
 - enqueueing more than Q elements causes an "overflow" error
 - Q.head is the position of the "head" of the queue
 - Q. tail is the first empty position at the tail of the queue

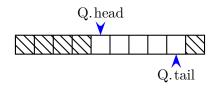
Enqueue(Q,x)if Q. queue-full 1 $\mathbf{2}$ error "overflow" 3 else Q[Q.tail] = xif Q.tail < Q.length4 5Q.tail = Q.tail + 16 else Q.tail = 1if Q.tail == Q.head7Q.queue-full = true8 9 Q.queue-empty = false

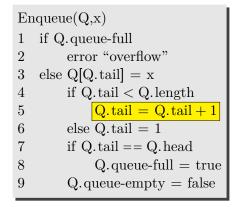


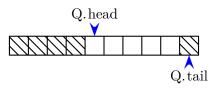
Enqueue(Q,x)if Q. queue-full 1 $\mathbf{2}$ error "overflow" 3 else Q[Q.tail] = xif Q.tail < Q.length 4 5Q.tail = Q.tail + 1else Q.tail = 16 7if Q.tail == Q.head Q.queue-full = true8 9 Q.queue-empty = false



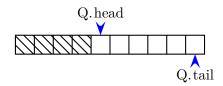
Enqueue(Q,x)if Q. queue-full 1 $\mathbf{2}$ error "overflow" 3 else Q[Q.tail] = xif Q.tail < Q.length 4 5Q.tail = Q.tail + 16 else Q.tail = 17if Q.tail == Q.head Q.queue-full = true8 9 Q.queue-empty = false

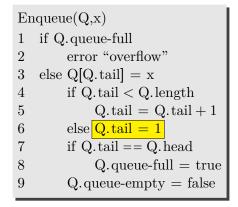


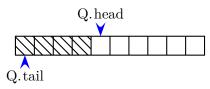




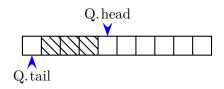
Enqueue(Q,x)if Q. queue-full 1 $\mathbf{2}$ error "overflow" 3 else Q[Q.tail] = xif Q.tail < Q.length 4 5Q.tail = Q.tail + 16 else Q.tail = 17if Q.tail == Q.head Q.queue-full = true8 9 Q.queue-empty = false

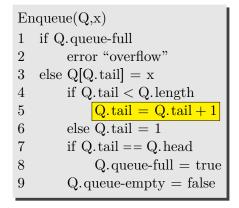


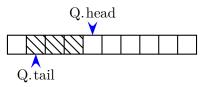




Enqueue(Q,x)if Q. queue-full 1 $\mathbf{2}$ error "overflow" 3 else Q[Q.tail] = xif Q.tail < Q.length 4 5Q.tail = Q.tail + 1else Q.tail = 16 7if Q.tail == Q.head Q.queue-full = true8 9 Q.queue-empty = false



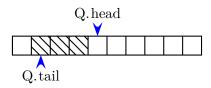




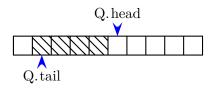
Dequeue(Q)if Q. queue-empty $\mathbf{2}$ error "underflow" 3 else x = Q[Q.head]if Q.head < Q.length 4 5Q.head = Q.head + 1else Q.head = 16 7if Q.tail == Q.head 8 Q.queue-empty = true9 Q.queue-full = false10 return x



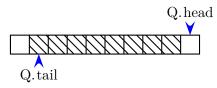
Dequeue(Q)		
1	if Q. queue-empty	
2	error "underflow"	
3	else $x = Q[Q.head]$	
4	if $Q.head < Q.length$	
5	Q.head = Q.head + 1	
6	else Q.head $= 1$	
7	if $Q.tail == Q.head$	
8	Q.queue-empty = true	
9	Q.queue-full = false	
10	return x	



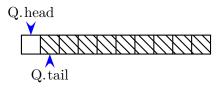
Dequeue(Q)if Q. queue-empty $\mathbf{2}$ error "underflow" 3 else x = Q[Q.head]if Q.head < Q.length 4 Q.head = Q.head + 15else Q.head = 16 7if Q.tail == Q.head 8 Q.queue-empty = true9 Q.queue-full = false10 return x



Dequeue(Q)if Q. queue-empty $\mathbf{2}$ error "underflow" 3 else x = Q[Q.head]if Q.head < Q.length 4 5Q.head = Q.head + 1else Q.head = 16 7if Q.tail == Q.head 8 Q.queue-empty = true9 Q.queue-full = false10return x



Dequeue(Q)if Q. queue-empty $\mathbf{2}$ error "underflow" 3 else x = Q[Q.head]if Q.head < Q.length 4 5Q.head = Q.head + 1else Q.head = 1 6 if Q.tail = = Q.head78 Q.queue-empty = true9 Q.queue-full = false10 return x



- Scheduling (disk, CPU)
- Used by operating systems to handle congestion.
- Algorithms (we'll see): breadth-first search.

Algorithm	Complexity
Stack-Empty	O(1) ✓
Push	O(1) ✓
Pop	O(1) ✓
Enqueue	O(1) ✓
Dequeue	O(1) ✓
Restrictions:	LIFO/FIFO orders only. \times

- Like queues but can enqueue/dequeue at both ends.
- Can modify the code for queues, add two more procedure.
- do it !
- Complexity scorecard: similar to queues.

Major problem this semester:

Represent a set S whose elements may vary through time. May want to perform some of:

- INSERT(S,x)
- DELETE(S,x)
- \bullet SEARCH(S,x). Result YES/NO. Better: handle for x, if found.
- MIN(S)
- MAX(S)
- SUCC(S,x), PRED(S,x)

- Stacks: dynamic sets with LIFO order.
- Queues: dynamic sets with FIFO order.

Dictionary

- A dictionary is an abstract data structure that represents a set of elements (or keys)
 - a dynamic set

- A dictionary is an abstract data structure that represents a set of elements (or keys)
 - a dynamic set
- Interface (generic interface)
 - $\bullet \ {\rm Insert}({\rm D},{\rm k}) \ {\rm adds} \ {\rm a} \ {\rm key} \ {\rm k} \ {\rm to} \ {\rm the} \ {\rm dictionary} \ {\rm D}$
 - Delete(D, k) removes key k from D
 - $\bullet \ {\rm Search}({\rm D},k)$ tells whether ${\rm D}$ contains a key k

- A dictionary is an abstract data structure that represents a set of elements (or keys)
 - a dynamic set
- Interface (generic interface)
 - Insert(D, k) adds a key k to the dictionary D
 - Delete(D, k) removes key k from D
 - $\bullet \ {\rm Search}({\rm D},k)$ tells whether ${\rm D}$ contains a key k
- Implementation
 - many (concrete) data structures

- A dictionary is an abstract data structure that represents a set of elements (or keys)
 - a dynamic set
- Interface (generic interface)
 - $\bullet \ {\rm Insert}({\rm D},{\rm k}) \ {\rm adds} \ {\rm a} \ {\rm key} \ {\rm k} \ {\rm to} \ {\rm the} \ {\rm dictionary} \ {\rm D}$
 - Delete(D, k) removes key k from D
 - $\bullet \ {\rm Search}({\rm D},{\rm k})$ tells whether ${\rm D}$ contains a key ${\rm k}$
- Implementation
 - many (concrete) data structures
 - we'll see: hash tables

Direct-Address Table

• A direct-address table implements a dictionary

Direct-Address Table

- A direct-address table implements a dictionary
- The universe of keys is $U = \{1, 2, \dots, M\}$

Direct-Address Table

- A direct-address table implements a dictionary
- The universe of keys is $U=\{1,2,\ldots,M\}$
- Implementation
 - an array T of size M
 - each key has its own position in T

Direct-Address Table

- A direct-address table implements a dictionary
- The universe of keys is $U = \{1, 2, \dots, M\}$
- Implementation
 - an array T of size M
 - each key has its own position in T

Direct-Address-Insert(T, k)1 T[k] = true Direct-Address-Delete(T, k)1 T[k] = false

Direct-Address-Search(T, k) 1 return T[k]

Direct-Address Table (2)

• Complexity

All direct-address table operations are O(1)

All direct-address table operations are O(1)

So why isn't every set implemented with a direct-address table?

All direct-address table operations are O(1)

So why isn't every set implemented with a direct-address table?

- Space complexity is $\Theta(|U|) \times$
 - |U| is typically a very large number—U is the universe of keys!
 - the represented set is typically much smaller than $|\mathbf{U}|$
 - i.e., a direct-address table usually wastes a lot of space

All direct-address table operations are O(1)

So why isn't every set implemented with a direct-address table?

- Space complexity is $\Theta(|U|) \times$
 - |U| is typically a very large number—U is the universe of keys!
 - the represented set is typically much smaller than $|\mathbf{U}|$
 - i.e., a direct-address table usually wastes a lot of space
- Want: the benefits of a direct-address table but with a table of reasonable size.

Direct Access Tables: Scorecard

Algorithm	Complexity
INSERT	O(1)√
DELETE	O(1)√
SEARCH	O(1)√
MEMORY:	$\theta(M) imes$

• Interface

- List-Insert(L, x) adds element x at beginning of a list L
- List-Delete(L, x) removes element x from a list L
- List-Search(L, k) finds an element whose key is k in a list L

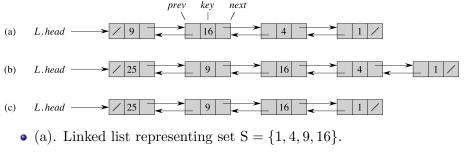
• Interface

- List-Insert(L, x) adds element x at beginning of a list L
- List-Delete(L, x) removes element x from a list L
- List-Search(L, k) finds an element whose key is k in a list L

• Implementation

- a doubly-linked list
- each element x: two "links" x. prev and x. next to the previous and next elements, respectively
- each element x: key x.key

Linked List: Implementation



- (b). After LIST-INSERT(S,25).
- (c). After LIST-DELETE(S,4).

List-Init(L) 1 L.head = NIL

List-Insert(L, x)

- $1 \quad x.next = L.head$
- 2 if L head \neq NIL
- $3 \qquad L.head.prev = x$
- 4 L.head = x
- 5 x. prev = NIL

List-Search(L, k) 1 x = L.head.next 2 while $x \neq NIL \land x$.key $\neq k$ 3 x = x.next 4 return x

Linked List: Implementation (II)

List-Delete(L, x) 1 if x.prev \neq NIL 2 x.prev.next = x.next 3 else L.head = x.next 4 if x.next \neq NIL 5 x.next.prev = x.prev

- instead of NIL sometimes convenient to have a dummy "sentinel" element L.nil
- Simplifies LIST-DELETE .
- Adds more memory ×.

List-Init(L) $1 \quad L.nil.prev = L.nil$ $2 \quad L.nil.next = L.nil$

List-Insert(L, x)

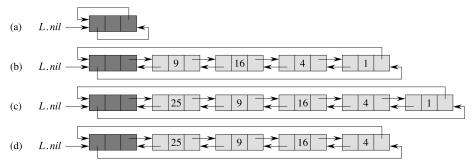
- $1 \quad x.next = L.nil.next$
- 2 L.nil.next.prev = x
- 3 L.nil.next = x
- 4 x.prev = L.nil

List-Search(L, k) 1 x = L.nil.next2 while $x \neq L.nil \land x.key \neq k$ 3 x = x.next4 return x

Linked Lists: Observations on Implementation

- Insert: at the head of the list.
- Possible: insert arbitrary position.

Circular Linked Lists



- Can use nil sentinel as head of the list.
- (a): empty circular list.
- (b): Linked list representing set $S = \{1, 4, 9, 16\}$.
- (c): After LIST-INSERT(S,25).
- (d): After LIST-DELETE(S,4).

Linked Lists: Scorecard

Algorithm

Complexity

List-Insert

Algorithm	Complexity
List-Insert	O(1) ✓
	<u>\</u>

List-Delete (with pointer)

Algorithm	Complexity
List-Insert	O(1) ✓
List-Delete (with pointer)	O(1) ✓
List-Search	

Algorithm	Complexity
List-Insert	O(1) ✓
List-Delete (with pointer)	O(1) ✓
List-Search	$\Theta(n)$ ×

- Can reimplement Stacks/Queues using Linked Lists.
- Implementation with pointers: will not pass the class if you don't know it !

• Idea

- $\bullet\,$ use a table T with $|T|\ll |U|$
- map each key $k \in U$ to a position in T, using a hash function

 $h:U\to \{1,\ldots,|T|\}$

• Idea

- use a table T with $|T| \ll |U|$
- map each key $k \in U$ to a position in T, using a hash function

 $h:U\to\{1,\ldots,|T|\}$

 $\begin{array}{l} Hash-Insert(T,k) \\ 1 \quad T[h(k)] = true \end{array}$

 $\begin{array}{ll} Hash-Delete(T,k) \\ 1 \quad T[h(k)] = false \end{array}$

 $\begin{array}{ll} Hash-Search(T,k) \\ 1 & return \ T[h(k)] \end{array}$

• Idea

- use a table T with $|T| \ll |U|$
- map each key $k \in U$ to a position in T, using a hash function

$$h: U \to \{1, \dots, |T|\}$$

 $\begin{array}{ll} Hash-Insert(T,k) \\ 1 \quad T[h(k)] = true \end{array}$

 $\begin{array}{ll} Hash-Delete(T,k) \\ 1 \quad T[h(k)] = false \end{array}$

 $\begin{array}{ll} Hash-Search(T,k) \\ 1 & return \ T[h(k)] \end{array}$

Are these algorithms always correct?

• Idea

- use a table T with $|T| \ll |U|$
- map each key $k \in U$ to a position in T, using a hash function

 $h: U \to \{1, \dots, |T|\}$

 $\begin{array}{l} {\rm Hash-Insert}({\rm T},{\rm k}) \\ 1 \quad {\rm T}[{\rm h}({\rm k})] = {\rm true} \end{array}$

 $\begin{array}{ll} Hash-Delete(T,k) \\ 1 \quad T[h(k)] = false \end{array}$

 $\begin{array}{ll} Hash-Search(T,k) \\ 1 & return \ T[h(k)] \end{array}$

Are these algorithms always correct? No!

• Idea

- use a table T with $|T| \ll |U|$
- map each key $k\in U$ to a position in T, using a hash function

$$h:U\to\{1,\ldots,|T|\}$$

 $\begin{array}{l} {\rm Hash-Insert}({\rm T},{\rm k}) \\ 1 \quad {\rm T}[{\rm h}({\rm k})] = {\rm true} \end{array}$

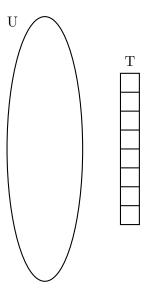
 $\begin{array}{ll} {\rm Hash-Delete(T,k)}\\ 1 \quad {\rm T[h(k)]} = {\rm false} \end{array}$

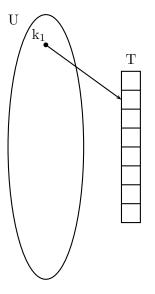
 $\begin{array}{ll} Hash-Search(T,k) \\ 1 & return \ T[h(k)] \end{array}$

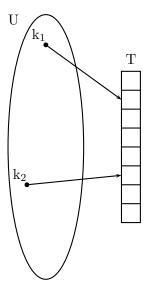
Are these algorithms always correct? No!

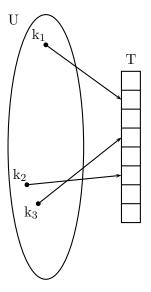
What if two distinct keys $k_1 \neq k_2$ collide? (I.e., $h(k_1) = h(k_2)$)

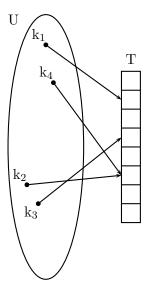
- Hash Tables: work well "on the average"
- Analogy: throw T balls at random into N bins.
- If $T \ll N$ (in fact $T = o(\sqrt{N})$ then with high-probability no two balls land in the same bin.
- Want our hash-function to be "random-like": elements of U "thrown out uniformly" by h onto elements of T.

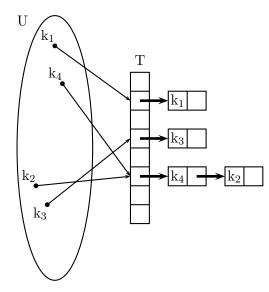


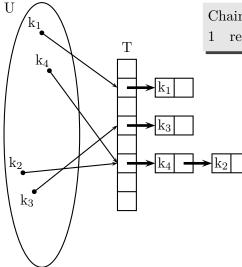






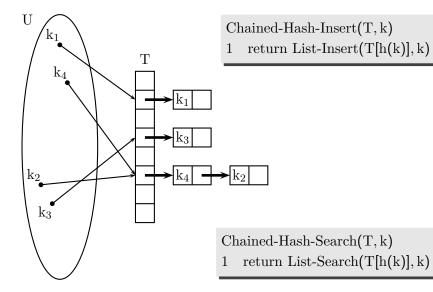




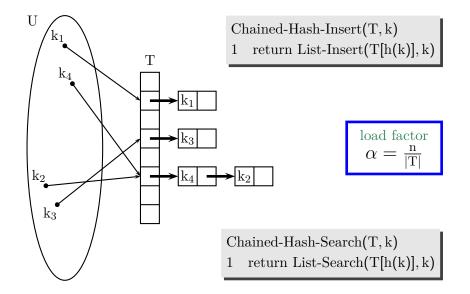


Chained-Hash-Insert(T, k)

1 return List-Insert(T[h(k)], k)



Hash Table: Chaining



• We assume uniform hashing for our hash function $h: U \to \{1 \dots |T|\}$ (where |T| = T.length)

• We assume uniform hashing for our hash function $h: U \to \{1 \dots |T|\}$ (where |T| = T.length)

$$\Pr[h(k)=i]=\frac{1}{|T|} \quad \text{ for all } i\in\{1\dots|T|\}$$

(The formalism is actually a bit more complicated.)

• We assume uniform hashing for our hash function $h: U \rightarrow \{1... |T|\}$ (where |T| = T.length)

$$\Pr[h(k) = i] = \frac{1}{|T|} \quad \text{ for all } i \in \{1 \dots |T|\}$$

(The formalism is actually a bit more complicated.)

 $\bullet\,$ So, given n distinct keys, the expected length n_i of the linked list at position i is

$$\mathbf{E}[\mathbf{n}_i] = \frac{\mathbf{n}}{|\mathbf{T}|} = \alpha$$

• We assume uniform hashing for our hash function $h: U \rightarrow \{1... |T|\}$ (where |T| = T.length)

$$\Pr[h(k) = i] = \frac{1}{|T|} \quad \text{ for all } i \in \{1 \dots |T|\}$$

(The formalism is actually a bit more complicated.)

 $\bullet\,$ So, given n distinct keys, the expected length n_i of the linked list at position i is

$$E[n_i] = \frac{n}{|T|} = \alpha$$

• We further assume that h(k) can be computed in O(1) time

• We assume uniform hashing for our hash function $h: U \rightarrow \{1... |T|\}$ (where |T| = T.length)

$$\Pr[h(k) = i] = \frac{1}{|T|} \quad \text{ for all } i \in \{1 \dots |T|\}$$

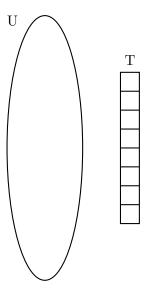
(The formalism is actually a bit more complicated.)

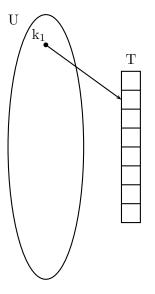
 $\bullet\,$ So, given n distinct keys, the expected length n_i of the linked list at position i is

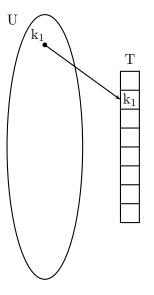
$$E[n_i] = \frac{n}{|T|} = \alpha$$

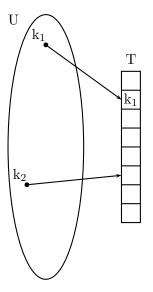
- We further assume that h(k) can be computed in O(1) time
- Therefore, the complexity of Chained-Hash-Search is

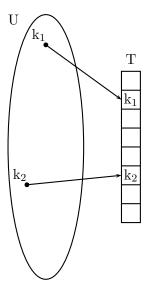
$$\Theta(1+\alpha)$$

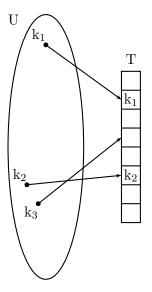


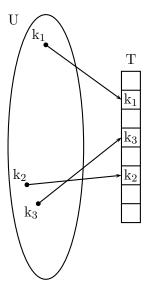


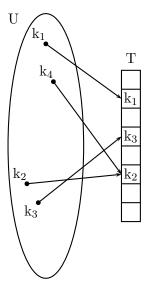


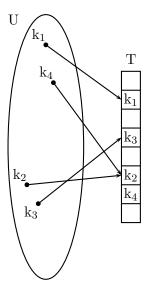


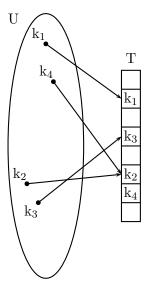












Hash-Insert(T, k) $1 \, j = h(k)$ $\mathbf{2}$ for i = 1 to T.length 3 if T[j] == nilT[j] = k4 5return j elseif j < T.length 6 7j = j + 18 else j = 1error "overflow" 9

- Idea: instead of using linked lists, we can store all the elements in the table
 - this implies $\alpha \leq 1$

- Idea: instead of using linked lists, we can store all the elements in the table
 - this implies $\alpha \leq 1$
- When a collision occurs, we simply find another free cell in T

- Idea: instead of using linked lists, we can store all the elements in the table
 - this implies $\alpha \leq 1$
- When a collision occurs, we simply find another free cell in T
- A sequential "probe" may not be optimal
 - can you figure out why?

Open-Addressing (3)

Hash-Insert(T, k) 1 for i = 1 to T.length 2 j = h(k, i)3 if T[j] == nil 4 T[j] = k 5 return j 6 error "overflow"

Open-Addressing (3)

Hash-Insert(T, k) 1 for i = 1 to T.length 2 j = h(k, i)3 if T[j] == nil 4 T[j] = k 5 return j 6 error "overflow"

• Notice that $h(k, \cdot)$ must be a permutation

 $\bullet\,$ i.e., $h(k,1),h(k,2),\ldots,h(k,|T|)$ must cover the entire table T